

16th ICCRTS

“Collective C2 in Multinational Civil-Military Operations”

Title of Paper

Information Sharing Between Platforms in DRDC's Networked Underwater Warfare Demonstration Trial

Topic(s)

Topic 9: Networks and Networking

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Report Documentation Page

Form Approved
OMB No. 0704-0188

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1. REPORT DATE JUN 2011	2. REPORT TYPE	3. DATES COVERED 00-00-2011 to 00-00-2011		
4. TITLE AND SUBTITLE Information Sharing Between Platforms in DRDC's Networked Underwater Warfare Demonstration Trial			5a. CONTRACT NUMBER	
			5b. GRANT NUMBER	
			5c. PROGRAM ELEMENT NUMBER	
6. AUTHOR(S)			5d. PROJECT NUMBER	
			5e. TASK NUMBER	
			5f. WORK UNIT NUMBER	
7. PERFORMING ORGANIZATION NAME(S) AND ADDRESS(ES) Defence R&D Canada - Atlantic, 9 Grove Street, PO Box 1012, Dartmouth, Nova Scotia B2Y 3Z7,			8. PERFORMING ORGANIZATION REPORT NUMBER	
9. SPONSORING/MONITORING AGENCY NAME(S) AND ADDRESS(ES)			10. SPONSOR/MONITOR'S ACRONYM(S)	
			11. SPONSOR/MONITOR'S REPORT NUMBER(S)	
12. DISTRIBUTION/AVAILABILITY STATEMENT Approved for public release; distribution unlimited				
13. SUPPLEMENTARY NOTES Presented at the 16th International Command and Control Research and Technology Symposium (ICCRTS 2011), Qu?c City, Qu?c, Canada, June 21-23, 2011. U.S. Government or Federal Rights License.				
14. ABSTRACT The final demonstration trial of Defence R&D Canada's (DRDC) Networked Underwater Warfare (NUW) Technology Demonstration Project (TDP) brought together 4 vessels and a reach-back centre to develop, maintain and share a single operating picture while performing anti-submarine warfare. Sensor information was shared by operators across platforms using network tools and chat applications in web pages and applications embedded within a DRDC developed Network Enabled Combat System (NECS). In all, 22 work stations were linked through a wireless UHF network using SubNet Relay (SNR) and via CFAV QUEST over satellite to a reach-back centre hosted at Canadian Forces Maritime Warfare Centre in Halifax. Aboard QUEST, 2 sets of NECS systems were installed; one set allowed the operators to exchange information with the other platforms and users and the other set using only the information available aboard QUEST from its sensors. This paper will begin by describing the network and the information sharing capabilities that were created. Noted differences between the set sharing information and isolated systems aboard QUEST will be highlighted. In addition, the importance and utility of a web service publishing information from the NECS will be described in detail.				
15. SUBJECT TERMS				
16. SECURITY CLASSIFICATION OF:			17. LIMITATION OF ABSTRACT Same as Report (SAR)	
a. REPORT unclassified	b. ABSTRACT unclassified	c. THIS PAGE unclassified		
18. NUMBER OF PAGES 51	19a. NAME OF RESPONSIBLE PERSON			

Abstract:

The final demonstration trial of Defence R&D Canada's (DRDC) Networked Underwater Warfare (NUW) Technology Demonstration Project (TDP) brought together 4 vessels and a reach-back centre to develop, maintain and share a single operating picture while performing anti-submarine warfare. Sensor information was shared by operators across platforms using network tools and chat applications in web pages and applications embedded within a DRDC developed Network Enabled Combat System (NECS). In all, 22 work stations were linked through a wireless UHF network using SubNet Relay (SNR) and via CFAV QUEST over satellite to a reach-back centre hosted at Canadian Forces Maritime Warfare Centre in Halifax. Aboard QUEST, 2 sets of NECS systems were installed; one set allowed the operators to exchange information with the other platforms and users and the other set using only the information available aboard QUEST from its sensors. This paper will begin by describing the network and the information sharing capabilities that were created. Noted differences between the set sharing information and isolated systems aboard QUEST will be highlighted. In addition, the importance and utility of a web service publishing information from the NECS will be described in detail.

Introduction

The Networked Underwater Warfare (NUW) Technology Demonstration Project (TDP) was undertaken by Defence R&D Canada (DRDC) to demonstrate future naval capabilities to carry out single and multiplatform UnderWater Warfare (UWW). The project began in 2001 with the demonstration sea trial occurring in May 2007 involving 4 naval platforms and a shore based reachback centre.

The project was initiated recognizing the potential benefits of Net-Centric Warfare (NCW). The objectives were broadly defined to demonstrate:

1. net-centric warfare constructs [1],
2. that the effectiveness of a naval force is increased by sharing information, and
3. situational awareness is increased by passing both sensor and track level information.

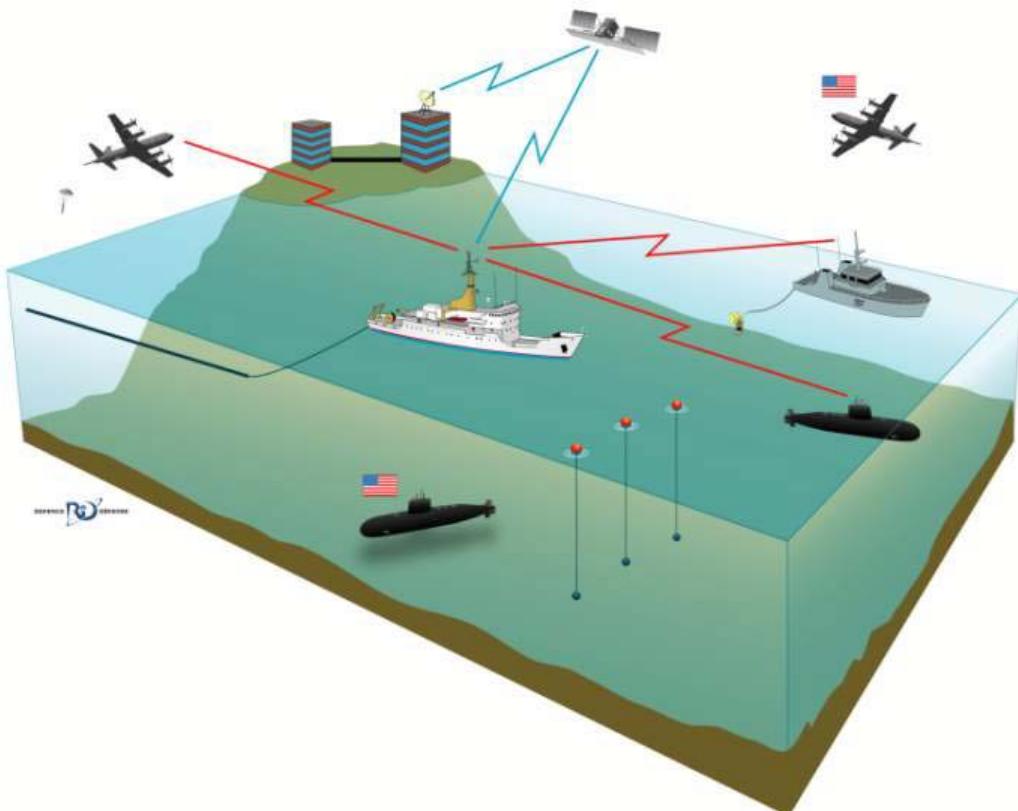


Figure 1 NUW Demonstration Trial

The demonstration concept was defined early in the project as an Anti-Submarine Warfare (ASW) exercise [2]. This choice gave the demonstration a real operational context and built on previous sonar system developments from DRDC's Towed Integrated Active Passive Sonar (TIAPS) TDP [3]. In this context, the demonstration conceived was a small task force as shown in Figure 1. The force consisted of a surface ship towing a line array, a Maritime Patrol Aircraft

(MPA) deploying sonobuoys, a submarine, and a Maritime Coastal Defence Vessel (MCDV) towing an active source. All platforms would share sensor information in real-time using SubNet Relay (SNR) * over UHF radios [4][5]. The force was connected by satellite communications to a shore-based reachback centre. Sonar operators on each platform and at reachback were permitted to share sensor information and collaborate through chat and other tools in order to demonstrate that by sharing information the Common Operating Picture (COP) could be formed more rapidly and accurately than the case where no information is shared.

In this paper, the information types and exchange requirements will be discussed followed by a description of the demonstration and the Network Enabled Combat System (NECS) that was created with web services. The paper will conclude with a discussion of some of the major results.

Information Exchange Requirements

Early in the project a team of knowledgeable ASW experts were assembled comprising DRDC scientists and engineers and sonar operators from the Canadian forces. The group was asked to identify what information could potentially be useful to sonar operators trying to detect, classify, localize and track underwater targets (submarines). This was a bottom up process in that the team set out to define what was required without reference to a data model. The findings of the group were the 12 types of data identified [6][7] for ASW operations as summarized in Table 1.

Table 1 NUW Data Types for ASW

	Data Type	Notes
1	Environmental Data	both measured and predicted acoustic properties
2	Receiver Information	includes acoustic sensor type, characteristics, and locations
3	Source Information	acoustic emitter or source characteristics and location
4	Echo Repeater Information	characteristics of device during testing and trials
5	Ping Information	waveform descriptions, ping schedules, ping status such as successful or missed transmission
6	Main Blast Data	information such as time and strength of received acoustic signal which traveled by direct path from the source
7	Feature Data [†]	received acoustic information such as tones or active sonar returns
8	Contact Data [†]	features that are likely related to a real platform
9	Track Data [†]	a set of features or contacts describing the path or course of a platform
10	Sonograms	raw acoustic data or images from raw acoustic data
11	Email and Chat Messages	to facilitate discussions between users for problem solving and to improve COP accuracy
12	Tactical Information	such as movements, sonobuoys drop areas, and other

* The SNR units were obtained from IP Unwired Inc. which is now a part of Rockwell Collins Government Services Canada Inc.

[†] Since the definitions vary in the literature causing confusion a consistent set of definitions for feature, contact and track [8] were adopted early in the project.

	command messages
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Having identified the pertinent data types the next issue was to solve the problem of information delivery and expected quantities of data. Both LINK 11/16 and LC2IEDM were examined [6] and were found, at the time, lacking the breadth and fidelity required. In the end, a binary messaging format was created containing all of the expected data types which could be exchanged over IP based networks [9].

In addition to the data model, communication rates had to be considered. The data link chosen for the demonstration was SubNet Relay (SNR) using existing tactical radios (WSC-3 (surface ship) and ARC-210 (air)). SNR supports Internet Protocol (IP) based networking and has the advantage of managing the data links. Transparent to the operator, SNR automatically handles disconnects and reconnections and will dynamically allocate bandwidth based on data load from each networked node. The UHF radios used in the demonstration are line of sight units and are therefore susceptible to generating network disconnects resulting from manoeuvring. The SNR network management feature mitigated the impact of these disconnects by automatically reconnecting and recovering communications when the link was restored.

Yet another issue is the heavy demand on the network for communication flow in a tactical environment. Even though SNR buffers data for transmission and reallocates bandwidth, it does not mean that important information will be transmitted in a timely manner. The total bandwidth available in NUW was 64 kilobytes per second – divided over the SNR nodes. In addition, SNR does not have sufficient privilege capability in its buffer to reorganize the outgoing tactical data. There is a priority layer in SNR but it handles network configuration and allocation issues, not the IP data being passed through the unit[†]. This means data has to be compact and that new information management and priority policies had to be implemented. Further, the priority handler and data buffering had to happen on the classified side, before transmission through the KG-84 encryption unit into the SNR unit. It was recognized that the prioritization scheme and mechanism had to be flexible since each platform had its own interests and that those interests, and thus priority, may change with operational phase and with the unit's role, objectives, and capabilities. An example priority matrix is given in Table 2. Note that the priority or value within an operational phase decreases to the right and the timeliness or urgency of the data increases going downward. Through examination one can see that the combined priority increases diagonally downward to the left in the table. Such a combined priority set makes sense since, for instance, a platform may be tracking a target while staying vigilant to the possibility of a second target thus performing in two operational phases at once; tracking and detection.

Priority settings for each platform was configured through a simple web interface as shown for the MPA subscriptions to the MCDV data in Figure 2. This interface allows each platform to set up data subscriptions with the data sources, setting both the period for updates the assigned priority.

[†] Even if SNR could handle a priority scheme there exists technical and policy hurdles of moving that information between classified and open domains through encryption equipment.

NUW

Name	Subscribe		
	Period	Priority	
Ping Notifications	1 min	Medium	Subscribe
Track Data	1 min	Medium	Subscribe
Buoy Data	1 min	Medium	Subscribe
Feature Data	1 min	Medium	Subscribe
Chat Data	1 min	Medium	Subscribe

NUW

Figure 2 MPA Data Subscription Page for MCDV Data

The protocol used on the network was also considered. Most network transactions are TCP/IP (Transport Control Protocol/Internet Protocol) which is a point to point data transmission. TCP/IP is reliable but feeds each user individually so when a number of users require the same data more transmission bandwidth is required to serve each request. A more efficient way would be to use UDP/IP (User Datagram Protocol/IP). UDP/IP broadcasts the data simultaneously to all connected users. This can greatly reduce bandwidth but does not have the data recovery services of TCP/IP. The choice made in the NUW network was to primarily use UDP for direct data sharing between systems since the subnet of users were all interested in similar data. Thus the competition on bandwidth is over priority with the consequence that all platforms received the data as long as it was broadcast. It was felt that the possible loss of data was a manageable risk. Studies were undertaken to ensure this was an understood risk and that bandwidth was sufficient. For this, models of the SNR network with the expected data loads were created in MATLAB[10] and Extend[11]. Even though UDP was used, TCP/IP was used for web based services as this information (described later) contains information for specific users.

Table 2 Example Information Priority Matrix with Operational Phase
Decreasing Value

	Must Have	Good to Have	Nice To Have
Search and Detection (I)	Sonograms Environmental Data Contact Data Source Information Ping Information Tactical Information	Receiver Information Email/Chat Main Blast Data Feature Data	Track Data
Localization and Classification (II)	Environmental Data Contact Data Track Data Tactical Information Source Information Ping Information	Email/Chat Receiver Information Main Blast Data Sonograms Feature Data	
Prosecution (III)	Source Information Ping Information Track Data Tactical Information	Contact Data	Email/Chat Feature Data Environmental Data Main Blast Data Sonograms Receiver Information
Post Prosecution	This has elements of both Search and Detection and Localization and Classification		

NUW Demonstration Trial

The NUW demonstration trial took place May 2007 in Emerald Basin, approximately 60 nautical miles off the coast of Nova Scotia. The demonstration involved 4 platforms in an IP network using SubNet Relay over UHF radio. The task force consisted of CFAV QUEST as a “poor man’s” frigate, HMCS SUMMERSIDE (a Maritime Coastal Defence Vessel (MCDV)), the submarine HMCS CORNER BROOK (a diesel-electric submarine (SSK)), and a Convair 580 aircraft from Canada’s National Research Council (NRC) acting as a CP140 Aurora Maritime Patrol Aircraft (MPA). All platforms were connected via satellite link[§] through CFAV QUEST to a reachback support centre hosted at the Canadian Forces Maritime Warfare Centre’s (CFMWC) Battle Visualization Laboratory in Halifax (see Figure 3). Thus, as suggested in

[§] The Satellite Link utilized a Fleet 77 connection to DRDC where it entered CFXnet (Canadian Forces Experimentation network) to reach the CFMWC. The link was an encrypted 64 kilobit per second link and its use was transparent to the operators as QUEST acted as a bridge to complete the connection to reachback.

Figure 1, the aircraft communication to reachback would travel over SNR to QUEST where a connection to the satellite would automatically relay the information to the CFMWC.

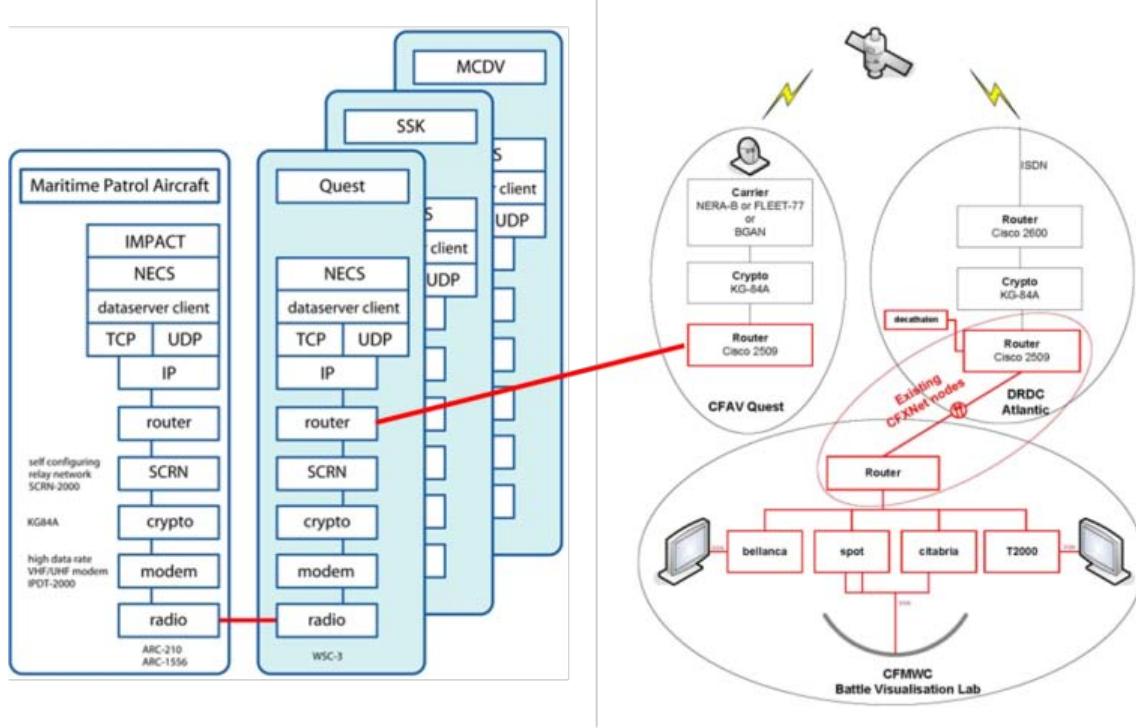


Figure 3 NUW Network. The SNR at-sea network showing the NECS and communication components is on the left and the satellite communication routing and components are on the right. The bridge on QUEST between SNR and the Satellite link is formed by connecting the routers

The network was set up as a peer-to-peer network so the trial did not rely on any one platform. This means there was no central control that defined the network, or its services. Thus, any node could drop out (or not show up) and the rest of the at-sea exercise could continue to collaborate and exchange data (the reachback connection could potentially be lost however that would not change the nature of the operation at sea). The loss of a platform was seen as a realistic scenario and the choice of peer-to-peer networking reduced the over-all risk to the demonstration trial.

A key element to the trial was the use of 2 sets of operators aboard QUEST. One set used only the information from sensors aboard QUEST while the second set had QUEST's sensor data as well as that provided over the network and could communicate via chat with the other vessels. Each set consisted of 2 operators – one compiling the picture while the other worked the lower level sensor data. Sufficient separation was maintained aboard so that they could not see each other's results. By using the same sensor data at the same time for the two sets one was able to observe the differences between networked and non-networked operators.

The trial occurred over several days, building complexity by adding connections to other platforms one at a time so that encountered problems could be addressed and the network could become more complex yet behave in an understandable way before full-scale demonstration commenced with a USN submarine joining the demonstration as a target.

The trial platforms and assets are summarized below:

1. CFAV QUEST; DRDC's research vessel emulated a frigate and was the task force command ship, the task force commander aboard was from the Canadian Forces (CF) Submarine Squadron (N32). QUEST's acoustic sensors were an SQR-19 towed array and sonobuoys (AN/SSQ-53(D)3 DIFAR). Four sonar operators were aboard from the Canadian Force's (CF) Acoustic Data Analysis Centre (ADAC). Additional non-acoustic sensors were QUEST's navigational radar, an AIS (Automatic Identification System) feed and XBTs (eXpendable Bathy Thermograph). The operators were divided into 2 teams: one team using only QUEST sensor information and the other sharing information with the rest of the task force.
2. NRC's 580 Convair aircraft was employed as an MPA. This choice was due to difficulty in scheduling a CP140 Aurora given their operational requirements. The pilots provided by NRC were ex-military and familiar with ASW operations. In preparation for the trial the aircraft was re-certified to drop sonobuoys. In addition to the pilots, TACNAV (Tactical Navigator) and sonar operators from CFB Greenwood's 14 Wing Maritime Proving and Evaluation Unit (MP&EU) flew aboard the aircraft to represent the balance of an MPA crew.
3. HMCS SUMMERSIDE was deployed with DRDC's Vertical Projector – 2 (VP2) [12] active sound source. This towed source gave the task force commander a multistatic capability. A major issue in multistatics is the exchange of ping characteristics and timing in order for other units to properly process the signals. This was not the case in the NUW network since the design was to freely exchange information. To the author's knowledge this was the first time a Canadian MCDV has participated in an ASW exercise
4. HMCS CORNER BROOK is a Canadian Victoria class submarine (SSK). It participated in the exercise, taking advantage of the COP picture before diving – and consequently, out of network contact. There was limited interfacing to its onboard sensors due to the scope of the project. The objective was in its operational use as part of the task force, communications, and the value of obtaining the COP prior to descent.
5. CFMWC Battle Visualization Lab hosted the reachback centre. This was a place for shore based expertise to engage in the operation and a demonstration of getting the COP to shore in real time.

Network Enabled Combat System (NECS)

The Network Enabled Combat System (NECS) is the sensor processing and display system present at each node (or platform) through which the operators interact, collaborate and build a common situational awareness. The system requirements were:

- An interface to sensors and processing. The sensor suite includes towed arrays (SQR19), sonobuoys (AN/SSQ-53(D)3 DIFAR), radar and AIS (Automatic Identification System).
- Acoustic displays for sonar analysis and to aid the operators in detection, localization and tracking.
- Methods for collaboration towards creating a Common Operating Picture.

- Generation and maintenance of system status notifications like which nodes or platforms are connected, their location and their equipment or sensor status.
- User-friendly tools that allow informal human interactions so that they can query, converse and exchange information such as chat, browsing of web pages and the exchange of files or other data.
- Components and software that are re-usable – such as offered in an open architecture. Potentially, many platforms and locations with different configurations could be involved so it has to be easy to enable different functionalities.

The obvious choice within DRDC-Atlantic was to use the System Test Bed (STB) [13] developed under the TIAPS TDP [3]. The STB offers an open architecture for information display and signal processing for a number of acoustic sensors. It is built using open source tools and with DISA's (Defense Information Systems Agency) Common Operating Environment (COE) Version 4.x [14] components for COP display and some track management functions **. The airborne version was “wrapped” around DRDC’s Integrated Multistatic Passive Active Concept Testbed (IMPACT) system [15] for airborne processing. The systems were quite different in each of the locations as seen in Figure 4 - using a wide variety of operating systems and computers.

To satisfy NUW TDP net-centric requirements additional functionality was added to the TIAPS version of the STB:

1. Extension of the data management to handle multi-platform data sources and communication.
2. A chat service for operator interaction. This was very similar to twitter™ [16] in that the allowed length of a chat message was limited to 256 bytes to prevent operators from becoming too verbose and with the desire that short succinct messages were more likely read and auctioned in a timely manner.
3. A common chart was created. All instantiations of NECS on the network work on a consistent set of underlying data. On an individual basis, each station views only the layers of interest and selects the view range, etc. as applicable. What was important in the data sets was not that each node maintains a completely identical data set but that the parts of interest and importance to a particular operator are consistent with the rest of the team. This is in contrast to trying to replicate all data everywhere which can only be achieved with very large bandwidths.
4. The addition of a web pages service to enhance the data exchange between operators. The web pages were automatically published by the NECS, including chart images, detailed track information, chat pages, chat histories, status, and document file exchanges and publishing.

The web page publishing capability is, to the author’s knowledge, unique for a tactical system. It allows the exchange of items that were not originally envisioned, such as orders, pictures and documents. Thus, this portal to information grants a great deal of flexibility to the system and can allow operators to quickly adapt to new situations. For example, during the NUW demonstration it was realized that there was no method for transferring XBT data between

** The STB has since been updated to remove dependence on COE components although they can still be used if desired. The STB is currently installed for some field trials as PLEIADES aboard HALIFAX Class Vessels, although without off board networking and with additional sonar capabilities than described here.

CFAV QUEST and the aircraft. A solution quickly evolved by scanning the XBT plot into an image document that was published on QUEST's webpage and then retrieved by personnel on the aircraft. Another advantage of a web service is that it provides the ability for disadvantaged units or extra terminals to be easily added to the operation since all that is required is a network connection and a web browser. Thus one can envision a scenario where a coalition vessel with no combat system could participate through a web-browser connected via SNR into the same network.

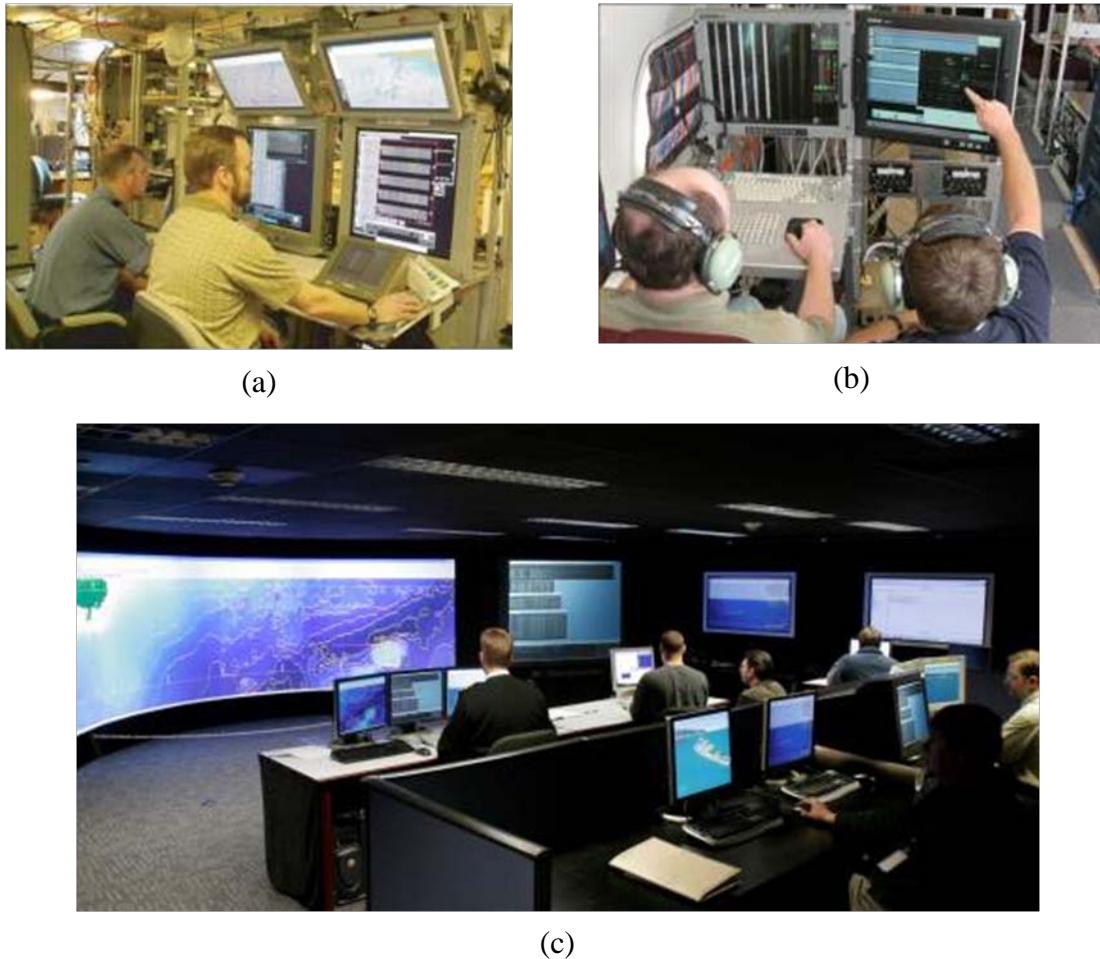


Figure 4 NECS (a) aboard CFAV QUEST (b) aboard the aircraft (c) at the shore based reachback

The NUW web pages were designed specifically for low bandwidth application [17] – hence the look was functional rather than eye catching as shown in Figure 5 through Figure 8. The entry page was a summary page (Figure 5). The summary page contains a summation of the current tracks, latest ping information, the most recent chat, status of the other connected platforms, and a link to the latest COP image as displayed on the platform's NECS. All pages were constructed with a site navigation area on the left for access to other pages containing COP histories, chat, chat history, data subscription setups, operator logs along with track data and more. Any of the web sites generated by any platform is quickly accessed by clicking on the vessel in the Platform Status area (labelled IES Summary). Thus, anyone on the aircraft could, for instance, connect to

CFAV QUEST by clicking on the word “QUEST” and then would be presented with QUEST’s summary page. The connected web service (or “Node”) was identifiable on all pages in the upper left corner of the page. This design allowed the network to operate as a peer to peer network yet made all the relevant web page data available to all. One NECS on each platform was chosen to generate the web pages for that unit.

The COP pages were generated by a full NECS publishing of the screen image at periodic intervals (set for 5 minutes during the demonstration) a sample of which is shown in Figure 6.

Name	Time	Latitude	Longitude	Altitude	Heading	Speed	Range	Bearing
MPA	088:1544:21.575 29 MAR 2007	**.**.**N	**.**.**W	2599.8	359.0	166.4	000.0	0.0
B06	088:1543:54.000 29 MAR 2007	**.**.**N	**.**.**W	0.0	000.0	0.0	019.5	174.3
B15	088:1544:04.000 29 MAR 2007	**.**.**N	**.**.**W	0.0	000.0	0.0	018.8	186.8
B03	088:1544:14.000 29 MAR 2007	**.**.**N	**.**.**W	0.0	000.0	0.0	014.4	185.5
IM01	088:1544:00.348 29 MAR 2007	**.**.**N	**.**.**W	0.0	015.0	9.0	012.8	183.8

Name	Src/Name	PingTime	Latitude	Longitude
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Platform	Time	Sequence	PRate	Q Size	UDP Sent	UDP Recv	Latency	e_infl	e_dat	e_def	errors
MCDV	088:1544:10.000 29 MAR 2007	3497	1024	0	273	130	-1.8	95	175	0	0
MPA	088:1544:07.000 29 MAR 2007	5	2048	0	173	173	-1.0	0	0	0	0
QUEST	088:1544:22.000 29 MAR 2007	248	4092	0	188	268	5.4	17	85	0	0
SSK	088:1544:19.000 29 MAR 2007	75	8092	0	189	68	3.1	17	1	0	0
RB_CFMWC	088:1544:19.000 29 MAR 2007	75	8092	0	189	68	3.1	17	1	0	0

Figure 5 NECS entry page

Even though direct COP interactions could only be done at a full NECS station, the web pages provided the ability for others to join in the operation by adding additional information, giving suggestions, and gaining a sense of the operational tempo and, more importantly, provide awareness of the operational picture. An important method for collecting operator input was through the chat page shown in Figure 7 below. The page was very simple. There was a chat history shown of the last number of messages with a timestamp and a callsign identifier. There was a place to add a callsign so that others could recognize who was chatting and a single line to enter a line of chat into.

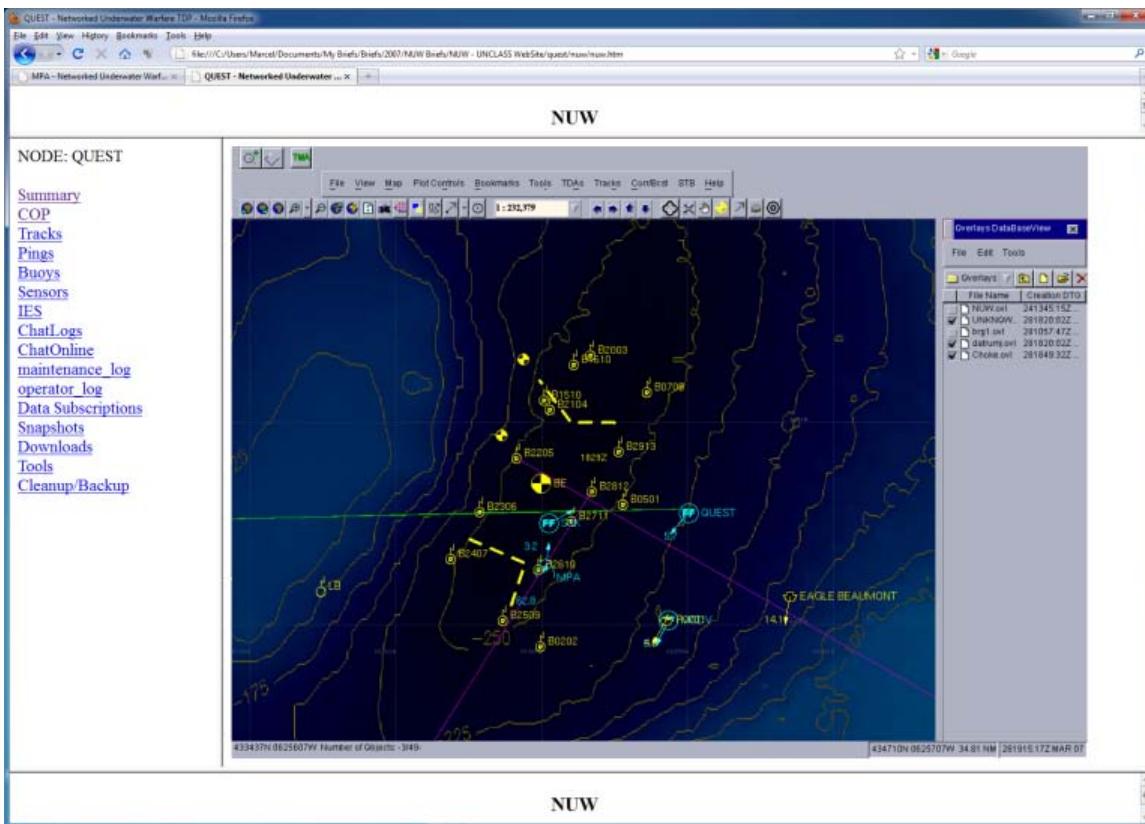


Figure 6 COP web page from CFAV QUEST

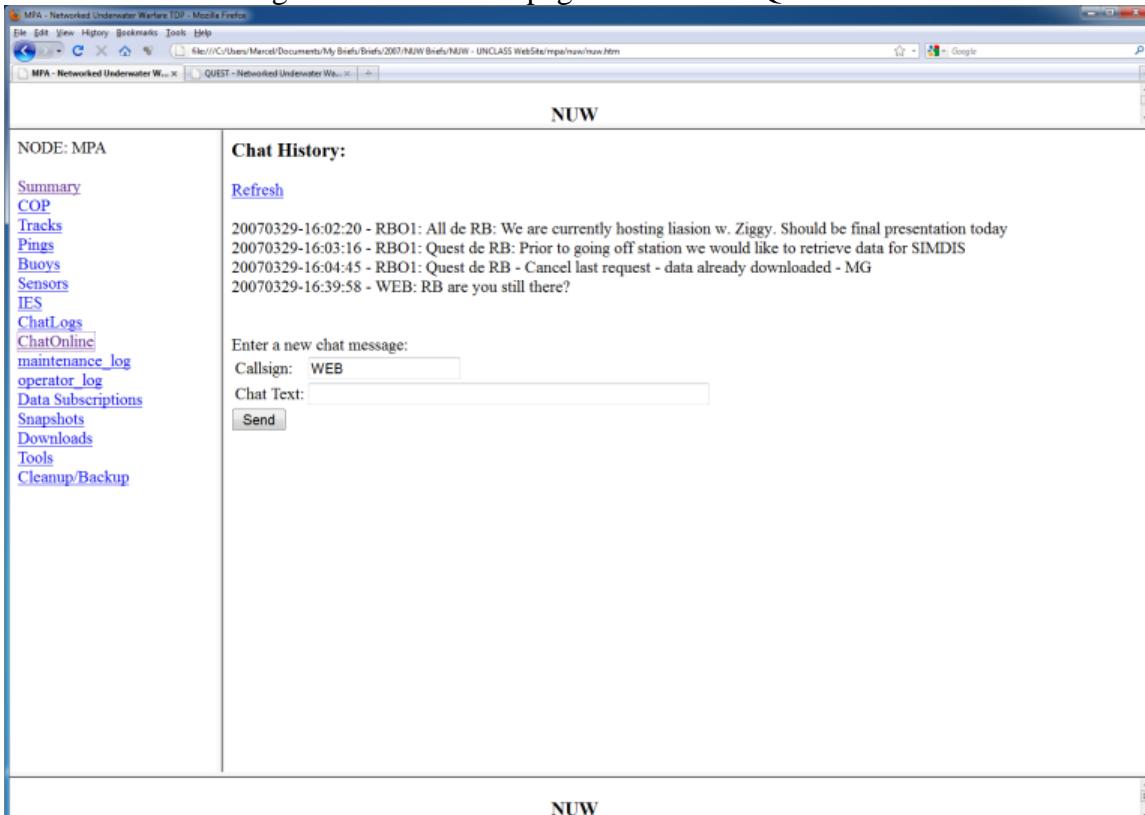


Figure 7 Chat Web Page

Equal in importance to chat is the operator log pages as shown in Figure 8. Operators could place or publish a document into the web service implemented aboard their respective platforms which others, in turn, could pick up. The importance was highlighted during the demonstration as the aircraft would start pulling documents from QUEST containing orders and acoustic data well before entering the operational area – thus becoming integrated into the operation immediately on arrival on station without a “catch-up” period to gain a picture of what was occurring.

Owing to the open architecture and NECS design approaches which delivered reusable code, many platforms and stations could be set up for the demonstration trial. In all there were over 20 displays connected to the network during the trial with 14 full NECS systems and 9 CPUs with web page browsers as shown in 0. Two were rapidly added during the trial. One was a quick fit prior to sailing to allow Command on the MCDV to participate more fully in the demonstration. The second was added by the task group commander aboard QUEST who had too much happening to handle the communications so assigned a person with a web station to the task.

NUW	
NODE: QUEST Summary COP Tracks Pings Buoys Sensors IES ChatLogs ChatOnline maintenance_log operator_log Data Subscriptions Snapshots Downloads Tools Cleanup/Backup	Archived Weblog: operator_log40802 <p>LRT x-platform received on MPA <small>[2007.03.28 20:22:18]</small> Attach: LRT-MPA-serial2813-xplat-2003Z.png - size: 240388 bytes time: 117.4 secs Quest generated x-platform and sent to MPA. MPA received and folded into surface. Image is of MPA surface after x-platform update.</p> <p>Serial 2809 corrected LRT w/COP Superimposed <small>[2007.03.28 20:05:01]</small> Attach: lrt_cop_combined_2809_quest.jpg - size: 96547 bytes time: 47.1 secs Previous post used wrong boundaries for LRT surface. Disregard prior message.</p> <p>LRT from Mar 28 serial 2813 <small>[2007.03.28 19:20:19]</small> Attach: MPA-LRT-track-serial2813-1909Zb.png - size: 59881 bytes time: 29.2 secs LRT Track on MPA at 1909Z</p> <p>MPA LRT Image <small>[2007.03.28 18:56:00]</small> Attach: lrt-serial2813-1842Z-mpa.png - size: 108448 bytes time: 53 secs MPA LRT Image. Getting very few MPA contacts. Time on file is approximate. No tracks yet created. Area of interest due north of BE, similar proximity to QUEST LRT image at nearly the same time.</p> <p>QUEST LRT Image <small>[2007.03.28 18:54:21]</small> Attach: lrt-2813-1842Z-quest.png - size: 80788 bytes time: 39.4 secs QUEST LRT image. Time on file approximate. No track yet created. Area of interest due north of BE</p>
NUW	

Figure 8 Operator Log page for retrieving files

Table 3 NECS and web browser locations in the NUW demonstration

Location	Description	NECS	Web Browser
CFAV QUEST	Stand-alone	2	
	Networked	2	
			3
HMCS CORNER BROOK	Headless	1	
	Laptop	1	
HMCS SUMMERSIDE		1	
	PC-Based	1	
			1
NRC Convair (MPA)	IMPACT	1	
	Laptop	1	
			2
CFMWC	Full NECS	2	
	PC-Based	2	
			3
Totals		14	9

*Shaded systems are attached to the NUW network

Achieving a Common Awareness

During the NUW demonstration a common situational awareness was achieved using the systems and networks to shared information. By design all operators worked on the consistent sets of data on the same picture. They interacted on the same picture and it was shared by all levels of command.

The shared information screen shown in Figure 9 was of benefit to sonar operators trying to detect and localize a target and to the task group commander wanting an immediate picture. Some examples of picture use are:

1. Cross fixes from shared data were easily performed. Possible target locations were identified where signal bearing lines from QUEST's towed array (in magenta) crossed those from sonobuoy data processed aboard the aircraft.
2. Blue Force tracking (self reporting of own track to other team members) was possible using the network. Each platform reported its own location into the network so, for instance, the fact that no radar was capable of tracking the aircraft did not matter since the aircraft continually updated its position through the network.
3. Operator/Platform engagement in the trial was continuous and at a high level of involvement. First because they had to be available to respond to the incoming chat but more because they were dealing with a continuous influx of data. It was observed more than once that the operators who were not networked would “go for coffee” when the ship went into a turn since a bent array meant the ship was blind. However, the

networked operator would stay at their station still having an awareness of the situation from other information feeds; hence they remained engaged even though the ship was technically blind. One of the results of this (shown in later analysis) is the force's increase in contact time with a target [18].

4. Operator confidence in the COP increases with corroboration. As the team of operators deployed across the network reaches consensus on the picture and the target their confidence increased more rapidly than the non-networked operators

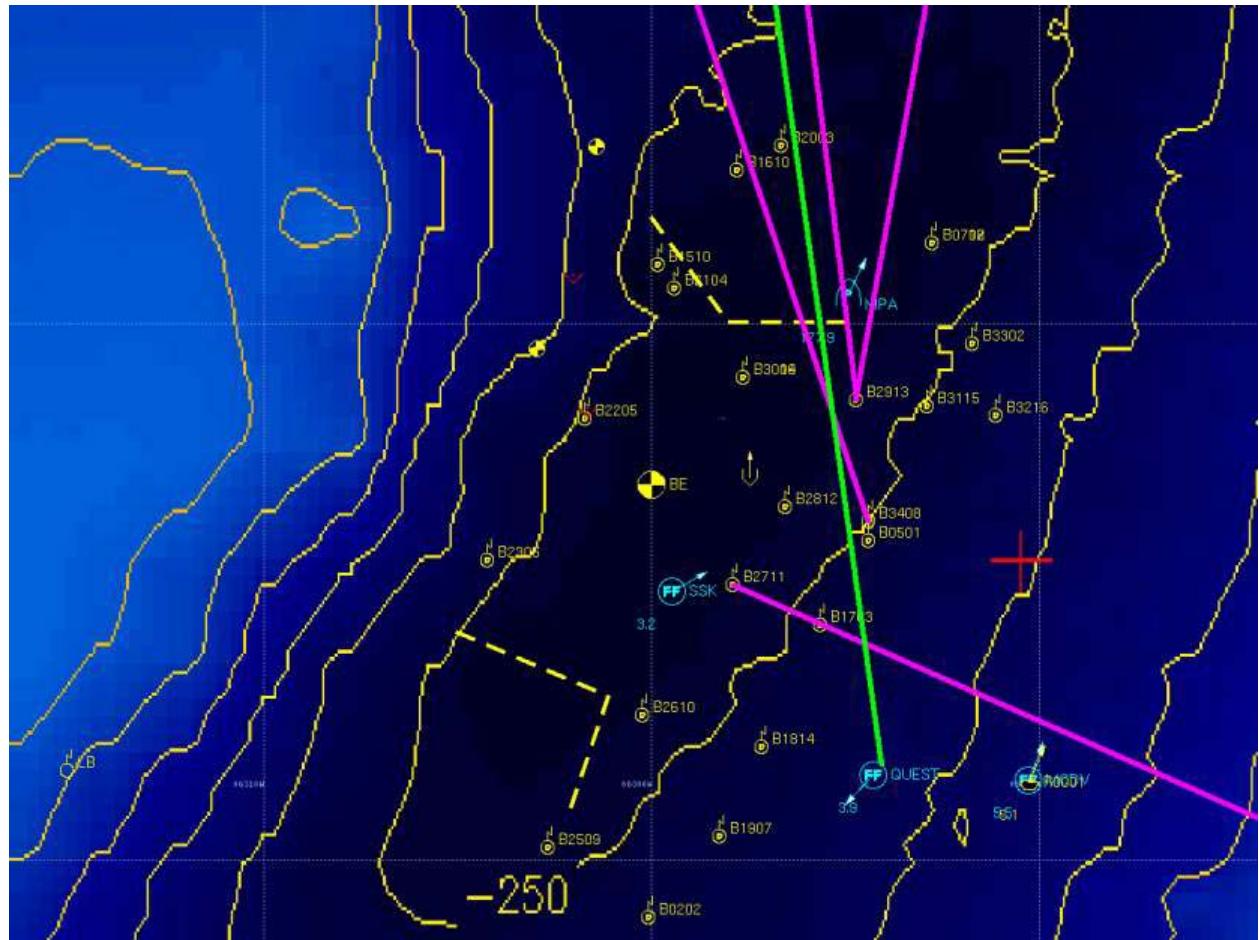


Figure 9 COP during NUW demonstration showing units (in blue, sonobuoys (yellow circles labelled B2205, B3216, etc.), sea bottom profile (yellow contours and blue shading) and cross fixes from more than one platform (green from towed array off CFAV QUEST and magenta from sonobuoy data taken from the aircraft)

The last point lends itself to the value of chat in an operation. Opening the communication channels between those solving the problem (ASW) allows for this increase in confidence. It was interesting to observe that even though chat is albeit an informal communication tool it did not take long for the operators to adopt a formal business style using radio-like jargon to convey information quickly and to compare notes.

The web page publishing capability of the combat systems (in this case NECS) was unique and used widely in the trial. Over a 3 day period the web page data served by CFAV QUEST to all users was 340MB. The portion served over just SNR to the submarine, MCDV and the aircraft was 45MB. Considering the size of most pages was minimal (less than 10kB), file sizes for a COP were typically 30kB, and that the bandwidth was limited this indicates that web use was large. An added benefit to the creation of the web pages is the ability to review the trial. At the end of the trial the entire website for each platform was placed on a single CD disc (500 MB). Thus, the website data itself can be easily accommodated in any future systems.

Conclusion

The NUW demonstration trial showed the art of the possible in net-centric warfare. It took the application of networking and networked systems and people to a real problem (ASW). The demonstration showed the common awareness and increase engagement that can be achieved through a shared picture and the enhancement that brings to the operators performance. There is a need now to decide how to use the capabilities demonstrated. Such as how best to use a reachback centre once it becomes aware. The context for demonstrating the effectiveness of Net-centric operations was that of an ASW exercise including multistatic sonar operations. In particular, multistatic sonar operations demanded the ability to exchange "ping coordination" information between the various platforms. The results of the experiment, from a multistatic sonar perspective, are still under investigation.

What NUW also demonstrated was that it is possible to conduct an exercise using peer to peer networks on very low bandwidth. The bandwidth lesson is essential even though it is certain more bandwidth will be added to networks in the future. It also is equally certain that as bandwidth increases so will demand for data and services. The result will be that the warfighter will always be constrained to fit his war (requirement) in an allocated bandwidth slice. Information management is essential to deal with this reality.

The NECS components, developed under this project, have now been added to the STB software baseline. As a result, the tools remain available for future development and demonstration

Acknowledgements

The NUW TDP demonstration involved many individuals. The Author would like to thank members of the following organizations for their involvement and support:

- Technology Demonstration Section members and Mechanical services staff at Defence R&D Canada – Atlantic
- The crews of CFAV QUEST, HMCS SUMMERSIDE and HMCS CORNER BROOK
- The Office of Naval Research (Networked Underwater Warfare Technology TRDP Project Arrangement No. CA-N-04-001)
- National Research Council Institute for Aerospace Research
- Canadian Forces Maritime Warfare Centre (CFMWC)
- Canadian Forces Meteorological and Oceanographic Operations Centre (METOC)

- MARLANT N31, N37 and N6)
- Maritime Operations Group (MOG5)
- CFB Greenwood 14 Wing MP&EU
- Canadian Forces Experimentation Centre (CFEC)
- General Dynamics Canada

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Information Sharing Between Platforms in DRDC's Networked Underwater Warfare Demonstration Trial

[Paper ID 172]
16th ICCRTS
Quebec City
21-23 June 2011

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- NUW TDP
 - Motivation
 - Objectives
 - Overview
- Information Exchange Requirements
 - Data
 - User
 - Information Priority
- NUW Demonstration Trial
 - Location
 - Participants
 - Network
- Network Enabled Combat System (NECS)
 - Software
 - System Features
 - Web Page Publishing
- Common Awareness
 - COP
 - Web Page Use
- Conclusions and Future

Motivation:

Requirement: The Need for Connectivity in Anti-Submarine Warfare (ASW):

- Cluttered, asymmetric, politically sensitive, littoral warfare environments
 - Need for rapid and accurate detection, classification and localization of potential targets
- Involvement of aircraft, ships and submarines of several nations
 - Uniform standards for comms and tactics and understanding
- Multistatic sonar operations
 - May be useless in the absence of real-time coordination



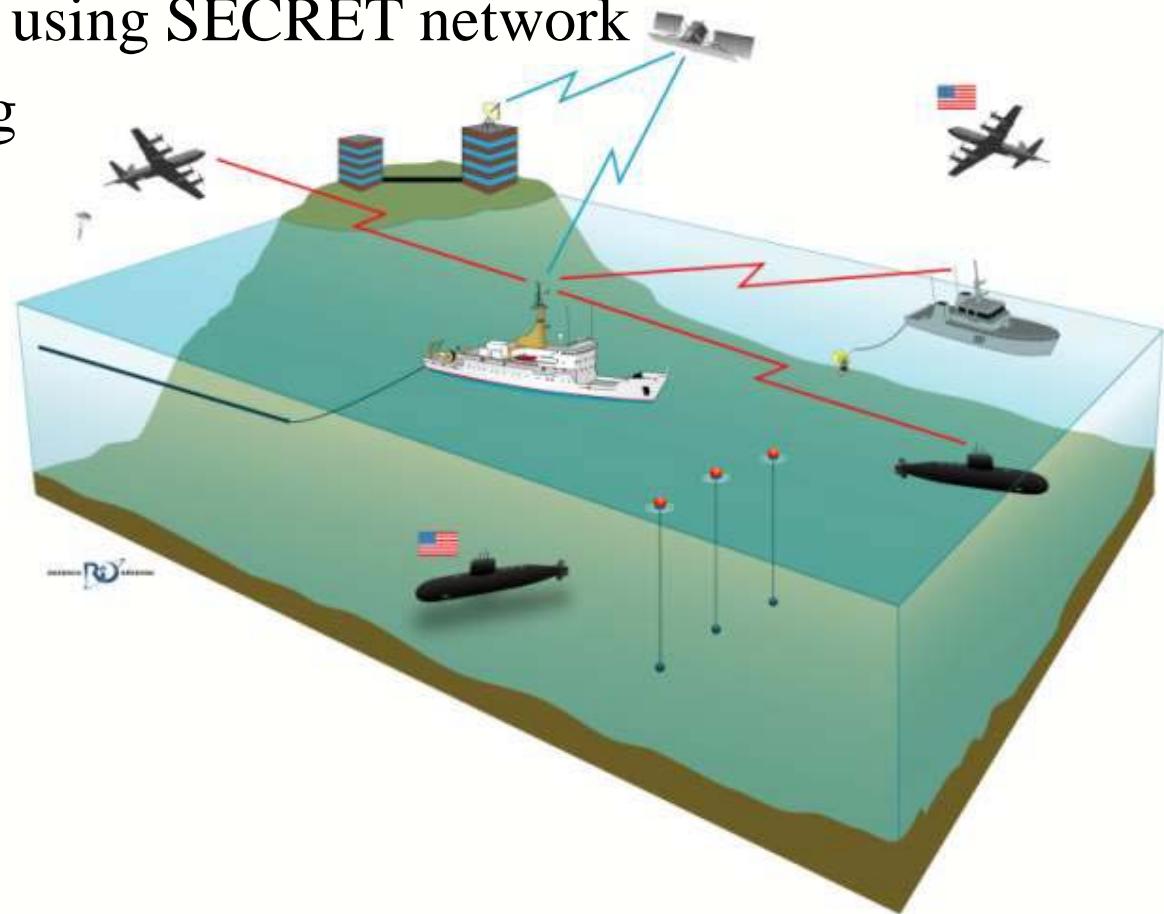
**Networked data exchange for
information sharing and coordination**

NUW - Objectives

- Develop and demonstrate technologies to fuse tactical sensor information to form and maintain an improved ASW portion of the Common Tactical Undersea Picture
- Improve the effectiveness of Underwater Warfare by investigating a flexible information/knowledge management architecture that can support several sonar systems and include land/air based sensors
- To demonstrate that the formation of the underwater portion of the COP (Common Operating Picture) can be done faster and more accurately by sharing information

NUW Demonstration Trial Concept

- Hi-level concept including platforms was formed early (2002-2003)
- allowed early engagement of parties of interest and early planning with N6 for network certification
- ASW operation
- Information exchange using SECRET network
- Initially 4 Nodes using UHF/SNR:
 - CFAV QUEST
 - MPA
 - MCDV
 - SSK
- Later (2005) added Reachback using inmarsat:
 - CFMWC
 - METOC



INFORMATION EXCHANGE REQUIREMENTS....

Information Exchange Requirements (TM2004-168)

- Used a bottom up approach
- Asked a team of underwater warfare scientists and sonar operators what type of information would be useful to have in an ASW operation
- Compared list with other standards (LINK) and JC3IEDM (emerging at time as LC2IEDM)
- Found no standard could cover requirement in detail and imposed bandwidth constraints

- 12 Data types required for ASW:
 - Environmental Data
 - Receiver Information
 - Source Information
 - Echo Repeater Information
 - Ping Information
 - Main Blast Data
 - Feature Data
 - Contact Data
 - Track Data
 - Sonograms
 - Email/Chat Messages
 - Tactical Information
- Added:
 - Web-pages (html)
 - Data files (doc, pdf, jpeg etc)

Detailed Information Example

Ping Information

- 3 sub-types:

Ping Status:

- Source ID
- Event Number
- Success or Failure Flag
- Source Level Measured (peak)

Next Ping information:

- Event number (each ping has a unique number for identification)
- Ping Source ID
- Next Wavetrain (either a Waveform/Wavetrain information structure or a reference Wavetrain ID)
- Start Time for Wavetrain
- Wavetrain Rate (period between wavetrains if applicable)
- Last ping in sequence notification as a notification to end processing or not to expect further pings.

Waveform/Wavetrain data:

- Wavetrain ID
- Wavetrain Name
- Wavetrain Source ID
- Wavetrain Start Time
- Number of Waveforms Forming the Wavetrain
- For each Waveform
 - Waveform ID
 - Waveform type (e.g. CW, FM)
 - Envelope type (e.g. Hamming)
 - Duration of waveform
 - Offset Time from start of wavetrain
 - Amplitude or source level
 - Source level reference (absolute/relative)
 - Characteristic Frequency 1 (e.g. Centre Frequency)
 - Characteristic Frequency 2 (e.g. Modulation Frequency)
 - Characteristic Frequency 3 (e.g. Bandwidth)
 - Sampled Waveform (To handle other waveforms)

Information Exchange for the User:

The system must provide:

- Only the information the operator needs when it is needed
- Tools to facilitate the formation of a Team distributed across all platforms and nodes
- Bandwidth Management
 - Setting information priorities
 - Information Push/Pull capability
 - Data subscriptions and notifications
- Consistent COP between platforms

IMPORTANT DESIGN CRITERION:

The COP need not be identical but it must be consistent!

Increasing Urgency

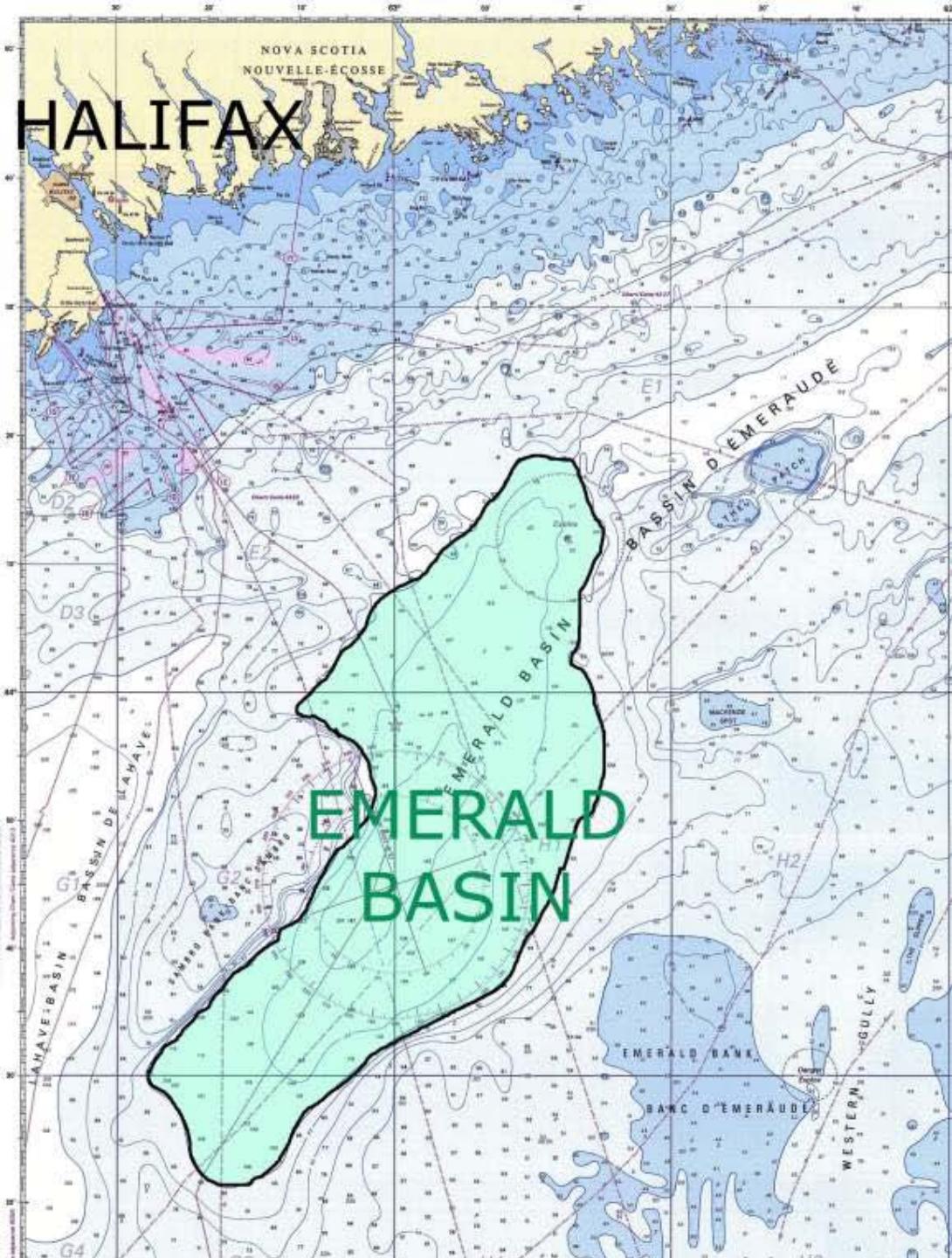
	Must Have	Good to Have	Nice To Have
Search and Detection (I)	Environmental Data Receiver Information Source Information Ping Information Contact Data Tactical Information	Other Tracks Email/Chat Main Blast Data Feature Data Sonograms	Track Data
Localization and Classification (II)	Environmental Data Receiver Information Source Information Ping Information Contact Data Track Data Tactical Information	Other Tracks Email/Chat Main Blast Data Feature Data Sonograms	
Prosecution (III)	Receiver Information Source Information Ping Information Track Data Tactical Information	Other Tracks Contact Data	Email/Chat Main Blast Data Feature Data Environmental Data Sonograms
Post Prosecution	This has elements of both Search and Detection and Localization and Classification		

NOTE: Only altered data is transmitted.

NUW MARCH 2007 SEA TRIAL....

Key Personnel and Organizations

- Project Manager: LCdr Lex Stuart DRDC
- Trial Chief Scientist: Byron Topp DRDC
- Scientific Authority: Marcel Lefrançois DRDC
- Sub Liaison Officer: Lt(N) Stephane Ouellet N32
- DRDC (NUW Technology Demonstration Project)
- ONR (Bilateral agreement to examine tracking technology)
- NAVAIR (BTEC (Battlespace Tactical Environmental Characterization))
- NRC (National Research Council (Canada) Convair 580 aircraft)
- CFMWC (Reachback cell hosting and added expertise)
- METOC (Environmental Predictions)
- N32 (MARLANT Sub Ops)
- MOG5 (Maritime Operations Group)
- MP&EU (Air Operators)
- ADAC (Sonar Operators)
- N6 (network accreditation and assistance)
- CFEC (CFXNet Satellite connection between CFAV QUEST and CFMWC)
- General Dynamics Canada (NECS/NUW system contractor)



Trial Location

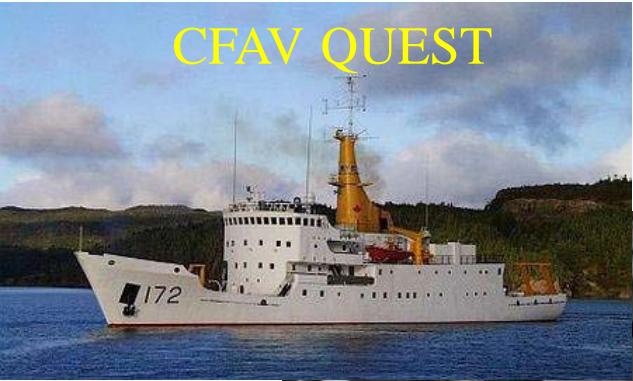
- Emerald Basin
- Approx 60NM from Halifax

Blue Force



HMCS
SUMMERSIDE

- Acoustic Source



CFAV QUEST

- Towed Array
- Radar
- AIS
- XBT
- Sonobuoys
- TF Command
- Sonar Operators



NRC Convair 580

- Sonobuoys
- TACNAV
- Sonar
Operators



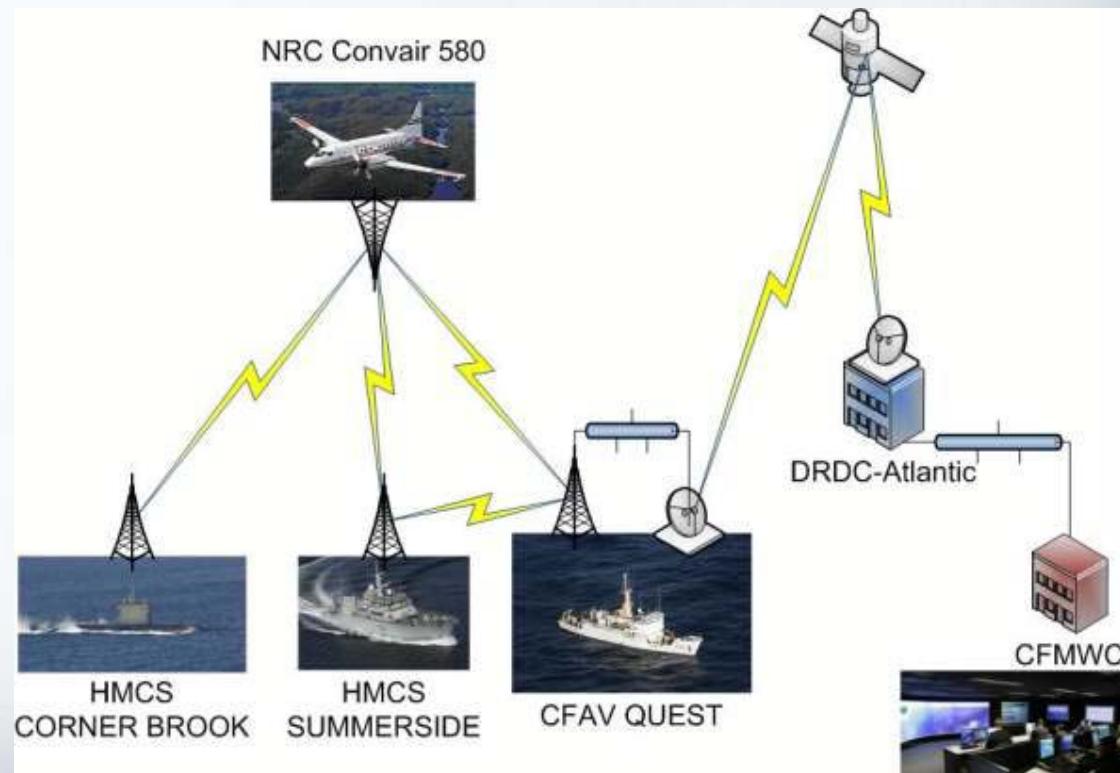
HMCS
CORNER BROOK



Reach-Back
(CFMWC)

NUW at-sea Network

- Uses Sub-Net Relay (SNR) from ipunwired (now Rockwell Collins)
- Over UHF radio (LOS) (ARC-210 on aircraft / WSC-3 on ships and SSK)
- 64 kilo-bit per second bandwidth (SNR and Satellite)
- SNR uses a slotted time management system to send data – slots are dynamically allocated depending on load
- GPS used to synchronize slot timing (accurate time base placed on SSK)
- Automatic connect after disconnect handled in SNR
- Will automatically form a data relay to other nodes (surface ships relay aircraft to SSK)
- Secret level – encrypted using KG84
- Seamless connection to Reach Back via QUEST using CFXnet (direct connection to at sea network)



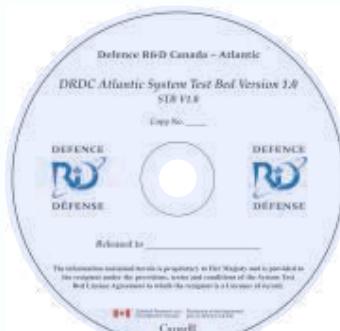
Target (SSN) (USS NORFOLK)



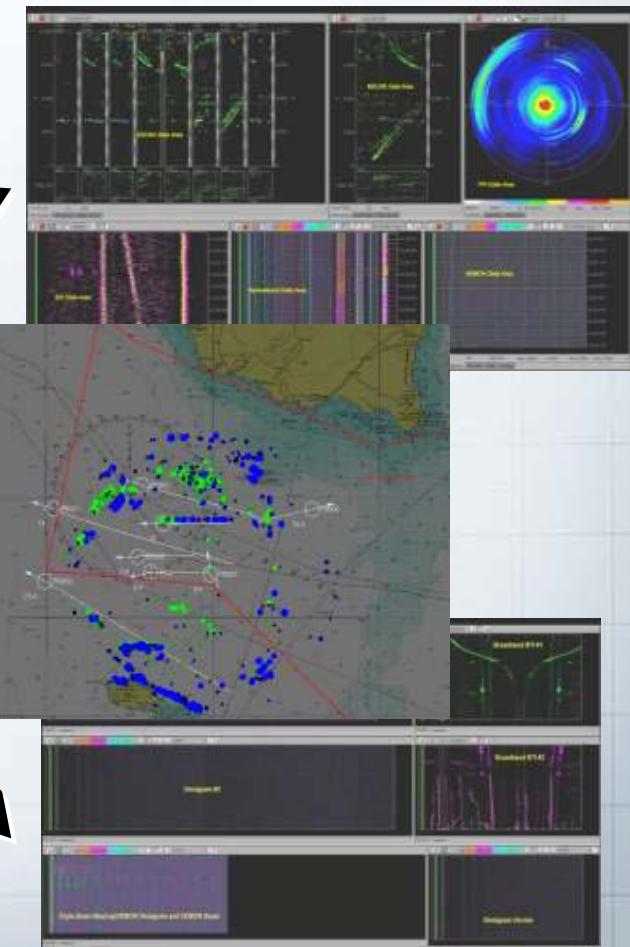
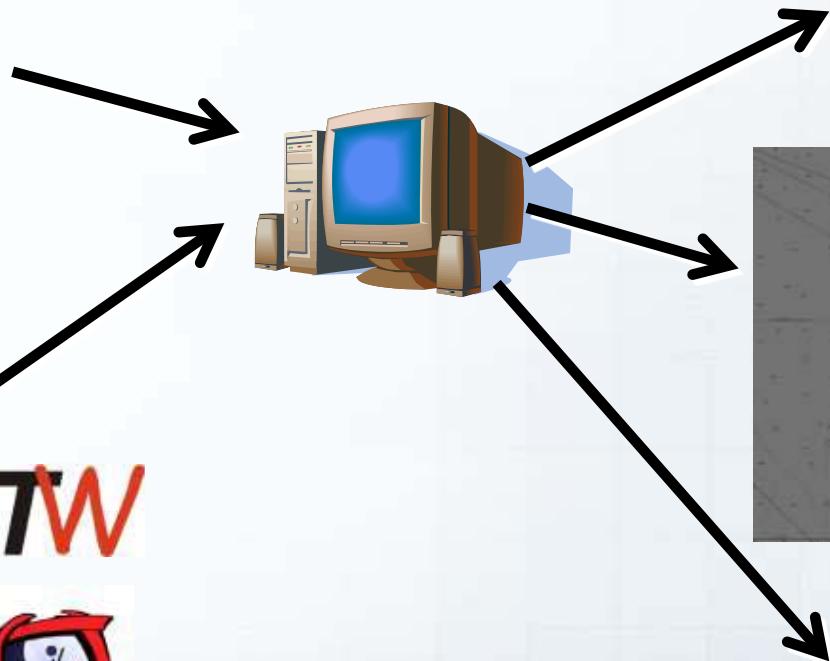
THE NETWORK ENABLED COMBAT SYSTEM (NECS)....

DRDC's System Test Bed (STB)

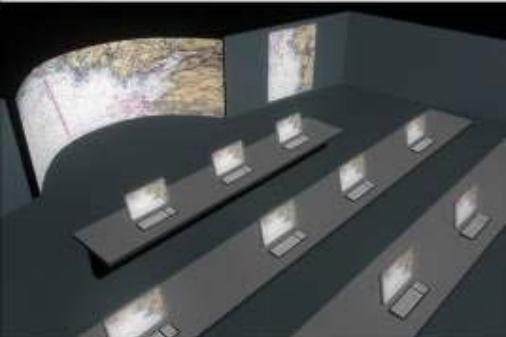
- A software toolbox providing data management, data processing, data interfaces and visualization functionality using open source tools.
- Derived from TIAPS TDP
- Encourages use of COTS equipment and high degree of code-reuse
- Built on an open architecture
- Current (2010) License distribution is STB V1.0



FFTW



The Network Enabled Combat System (NECS)



- Built through extending TIAPS version of STB
- Extensions added for collaborative information environment for COP compilation
- Features:
 - GCCS-M Chart Display
 - Display and/or process organic and other platform sensor data
 - Active and passive sonar
 - AIS
 - Radar
 - Blue Force Tracking
 - Chat over low bandwidth networks
 - Automatic web-page publishing from combat system for enhanced situational awareness and historical information – both within platform and off-platform pages can be accessed

NUW Web-site(s)

- These are created direct from Combat System (NECS) – there is one on each platform/node
- Web-pages service means disadvantaged units/stations can participate as long as they can attach a web-browser to the network
- No need for operator interaction to create complex web-page
- Intent is to pass data (give awareness)
- Allows for non-standard file publishing (the unexpected)
- Specific design for low-bandwidth (pages are not pretty – they are simple to reduce number of bytes)
- ASW portion of trial (about 4 days (8 hours each)) fits onto 1 CD (421MB)

NECS Entry/Summary page

Publishing
Node or Site

Track Summary

Summary page for node MPA

Last Update: 2007/03/29 15:44:24

Track Summary

Name	Time	Latitude	Longitude	Altitude	Heading	Speed	Range	Bearing
MPA	088:1544:21.575 29 MAR 2007	**.**.**N	**.**.**W	2599.8	359.0	166.4	000.0	0.0
B06	088:1543:54.000 29 MAR 2007	**.**.**N	**.**.**W	0.0	000.0	0.0	019.5	174.3
B15	088:1544:04.000 29 MAR 2007	**.**.**N	**.**.**W	0.0	000.0	0.0	018.8	186.8
B03	088:1544:14.000 29 MAR 2007	**.**.**N	**.**.**W	0.0	000.0	0.0	014.4	185.5
IMD1	088:1544:00.348 29 MAR 2007	**.**.**N	**.**.**W	0.0	015.0	9.0	012.8	185.5

Latest Pings

Name	SrcName	PingTime	Latitude	Longitude

Latest Chat Messages

Platform	Time	Sequence	PRate	Q Size	UDP Sent	UDP Recv	Latency	e_in	e_out	e_dat	e_del	Errors
MCDV	088:1544:10.000 29 MAR 2007	3497	1024	0	273	150	-1.8	0.5	175	0	0	0
MPA	088:1544:07.000 29 MAR 2007	5	2048	0	173	173	-1.0	0	0	0	0	0
QUEST	088:1544:22.000 29 MAR 2007	248	4092	0	188	268	5.4	17	85	0	0	0
SSK	088:1544:19.000 29 MAR 2007	72	8092	0	189	68	3.1	17	1	0	0	0
RB_CFMWC	088:1544:19.000 29 MAR 2007	75	8092	0	189	68	3.1	17	1	0	0	0

Last COP Image:

20070329-15:30:00

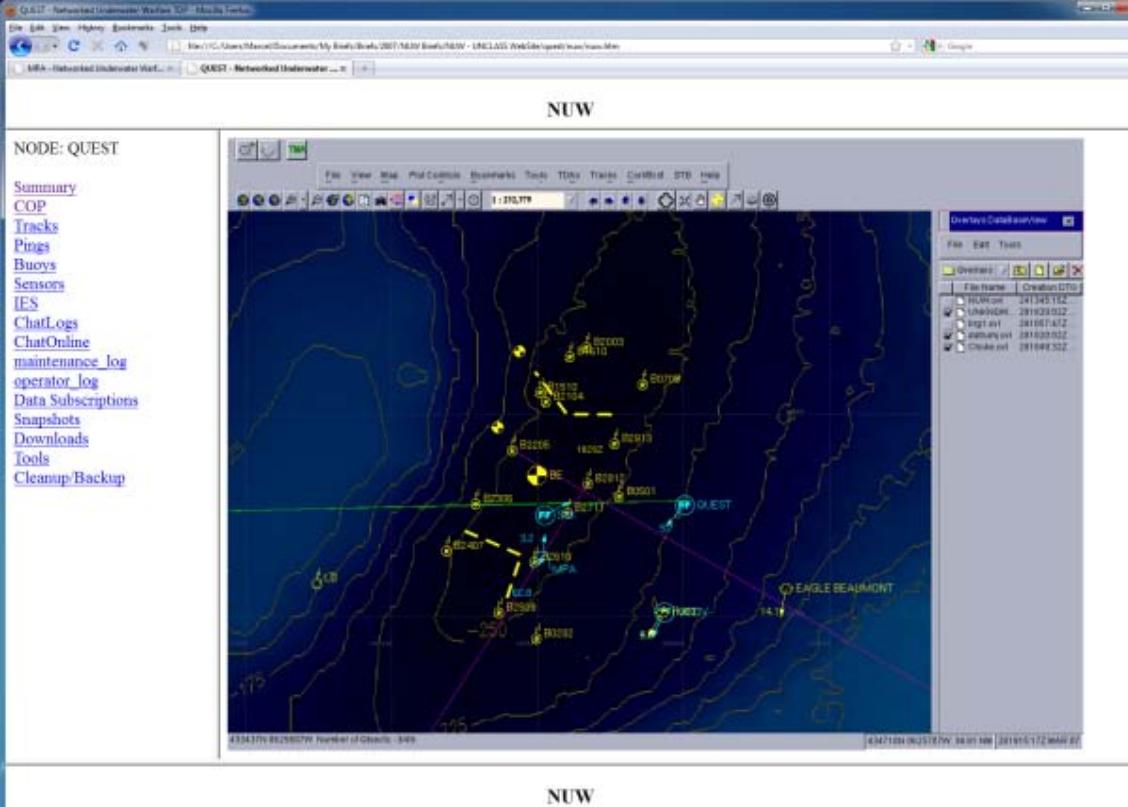
Site (Node)
Navigation Area

Link to latest COP

Latest Pings

Latest Chat
Messages

Links to
Connected
Nodes



Data Subscription Page

Shows data available from each site/node.

User may set up a subscription with an update interval and priority (low/medium/ high)

NUW

is available from platform MCDV

Summary
[COP](#)
[Tracks](#)
[Pings](#)
[Buoys](#)
[Sensors](#)
[IES](#)
[ChatLogs](#)
[ChatOnline](#)
[maintenance log](#)
[operator log](#)
[Data Subscriptions](#)
[Snapshots](#)
[Downloads](#)
[Tools](#)
[Cleanup/Backup](#)

NUW

Refresh
[Get History Status](#)

Name	Subscribe		
	Period	Priority	
Ping Notifications	1 min	Medium	Subscribe
Track Data	1 min	Medium	Subscribe
Buoy Data	1 min	Medium	Subscribe
Feature Data	1 min	Medium	Subscribe
Chat Data	1 min	Medium	Subscribe

COP Web Page

Current COP is added to site automatically at set intervals (operator may review history)

File Edit View History Bookmarks Tools Help

File C:\Users\Shared\Documents\My Books\Study 2001\NSW Books\NSW - SME103 Website\index.html

DEFENCE RD DÉFENSE

NUW

NODE: MPA

Chat History:

Refresh

20070329-16:02:20 - RBO1: All de RB: We are currently hosting session w/ Ziggy. Should be final presentation today

20070329-16:03:16 - RBO1: Quest de RB: Prior to going off station we would like to retrieve data for SIMDIS

20070329-16:04:45 - RBO1: Quest de RB - Cancel last request - data already downloaded - MG

20070329-16:39:58 - WEB: RB are you still there?

Enter a new chat message:

Callsign: WEB

Chat Text:

Chat became business-like with radio-like jargon to convey information and compare notes – this lead to increased confidence and greater engagement

Chat Web Page
Shows latest chat and allows one to send a one-line chat message

Callsign Entry

Chat Line

NUW

Operator Log Page
files/documents/pictures could be published and retrieved on web site

NUW

g: operator_log40802

LRT x-platform received on MPA
(2007.03.28 20:22:18)
Attach: [LRT-MPA-serial2813-xplat-2003Z.png](#) - size: 240388 bytes time: 117.4 secs
Quest generated x-platform and sent to MPA. MPA received and folded into surface. Image is of MPA surface after x-platform update.

Serial 2809 corrected LRT w/COP Superimposed
(2007.03.28 20:05:01)
Attach: [lrt cop combined 2809 quest.jpg](#) - size: 96547 bytes time: 47.1 secs
Previous post used wrong boundaries for LRT surface. Disregard prior message.

LRT from Mar 28 serial 2813
(2007.03.28 19:20:19)
Attach: [MP4-LRT-track-serial2813-1909Zb.png](#) - size: 59881 bytes time: 29.2 secs
LRT Track on MPA at 1909Z.

MPA LRT Image
(2007.03.28 18:56:00)
Attach: [lrt-serial2813-1842Z-mpa.png](#) - size: 108448 bytes time: 53 secs
MPA LRT Image. Getting very few MPA contacts. Time on file is approximate. No tracks yet created. Area of interest due north of BE, similar proximity to QUEST LRT image at nearly the same time.

QUEST LRT Image
(2007.03.28 18:54:21)
Attach: [2813-1842Z-quest.png](#) - size: 80788 bytes time: 39.4 secs
QUEST LRT image. Time on file approximate. No track yet created. Area of interest due north of BE.

NECS Locations: 14 systems + 9 PC's

- Varying functionality depending on platform capability.
- 9 Additional Web-browser PC's were connected:
(3) on QUEST, (2) MPA, (1) MCDV, (3) CFMWC.

Location	Number	Description	Notes
CFAV QUEST	1	Stand-alone	Using only data organic to QUEST
	1		
	1	Networked	Sharing information and collaborating with other platforms/nodes
	1		
CORNERBROOK	1	Headless	Chart generated internally (no display)
	1	Laptop	In Ops room providing interface and display
SUMMERSIDE	2	Solaris	In VP2 container plus terminal in Ops room (at Captain's Request)
NRC Convair	1	IMPACT	STB mated with IMPACT for sonobuoy processing
	1	Laptop	Terminal for TACNAV
CFMWC	2	Solaris	
	2	PC	Limited Chart capability

ACHIEVING A COMMON AWARENESS...

Common COP

- All connected platforms/operators worked simultaneously on the same COP thus insuring a common view
- Underlying data was shared – view (layers) individually selected

Sea bottom contours

Sonobouys

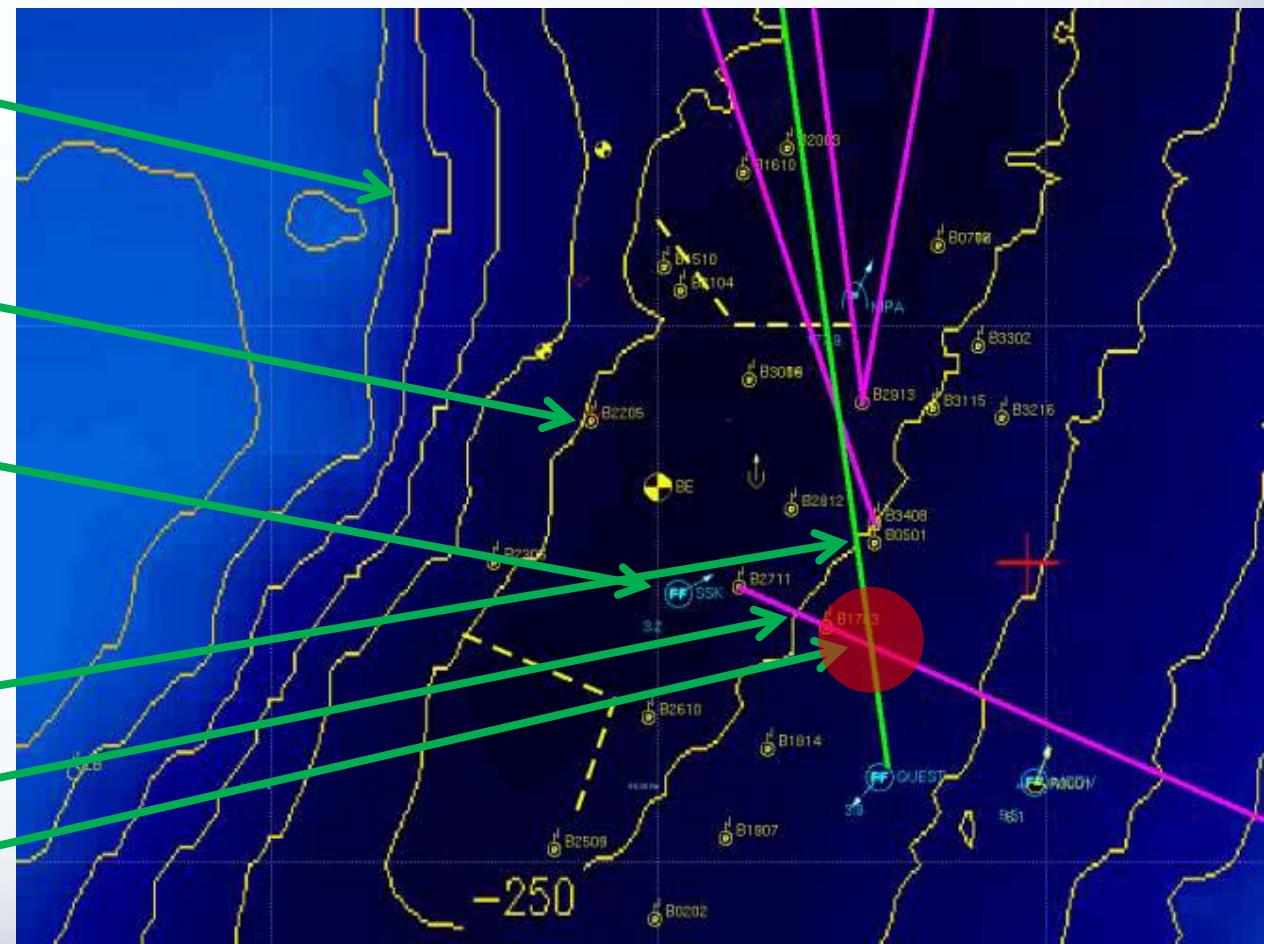
Blue Force tracking

Sonar contacts:

Towed array (green)

Sonobouy (magenta)

Possible Cross-Fix!!



Web Page Statistics for Demonstration Trial

All web pages served (organic and inorganic to node)						
	Total Trial					
	Sites	KBytes	Visits	Pages	Files	Hits
QUEST	14	271695	77	5664	16292	20048
MPA	16	9580	184	1329	1760	2608
MCDV	19	24614	140	804	998	1195
SSK	17	9726	110	751	1082	1599
RB	10	24443	250	2430	2989	4371
Web pages served over SNR and satelite (to other nodes)						
	Sites	KBytes	Visits	Pages	Files	Hits
QUEST	7	17351	40	559	924	1149
MPA	12	4933	95	632	814	1029
MCDV	15	16684	70	280	449	485
SSK	15	5426	90	612	858	1300
RB	4	1000	18	109	196	404

A total of 44.4MB over SNR in 4 days using a 64kb/sec connection filled with other traffic!
 (maintenance/ASW binary data/chat)

CONCLUSIONS...

Conclusions

- Demonstrated tactical level information exchange in an at sea ASW operation.
- Demonstrated that a common COP/SA can be formed through:
 - Sharing information at all levels (tactical commanders, reachback and sensor operators)
 - Exchanging tactical data generated from sensor processing in the combat systems (NECS using a priorities exchange)
 - The use of chat to increase collaboration, confidence and operator engagement
 - The use of combat system published and hosted web pages
- Demonstrated that information exchange in an ASW operation can be accomplished using a peer-to-peer network over a low-bandwidth.

What Next?

- Software is being maintained in DRDC's System TestBed (STB)
- Web-page improvements for future deployments/projects/investigation
 - Better interfaces
 - Improving web-page refresh rates
 - Use as an information portal in operations
 - Use as a data log for future sea trials
- ASW systems and information exchange for AMASE TDP (Advancing Multistatic Active Sonar Employment)
- Input/Advice on next generation combat system specifications??



Maritime Open Systems Architecture Integration Centre

Reusable and scalable information management and data processing systems built on PLEIADES and the STB



